

Description

The B40A40AC PWM servo drive is designed to drive brushless DC motors at a high switching frequency. A single red/green LED indicates operating status. The drive is fully protected against over-voltage, under voltage, over-current, over-heating and short-circuits across motor, ground and power leads. Furthermore, the drive can interface with digital controllers or be used stand-alone and requires only a single unregulated AC power supply. Loop gain, current limit, input gain and offset can be adjusted using 14-turn potentiometers. The offset adjusting potentiometer can also be used as an on-board input signal for testing purposes.

Power Range

| | |
|--------------------|--------------|
| Peak Current | 40 A |
| Continuous Current | 20 A |
| Supply Voltage | 45 - 270 VAC |


Features

- ▲ Four Quadrant Regenerative Operation
- ▲ DIP Switch Selectable Modes
- ▲ Adjustable Current Limits
- ▲ Differential Input Command
- ▲ Built in Shunt Regulator Circuit
- ▲ On-Board Test Potentiometer
- ▲ Offset Adjustment Potentiometer
- ▲ Adjustable Input Gain
- ▲ Selectable 120/60 Hall Commutation Phasing
- ▲ Hall Velocity Mode
- ▲ Encoder Velocity Mode
- ▲ Differential Encoder Feedback

MODES OF OPERATION

- Current
- Open Loop
- Hall Velocity
- Encoder Velocity
- Tachometer Velocity
- External/Analog Velocity

COMMAND SOURCE

- ± 10 V Analog

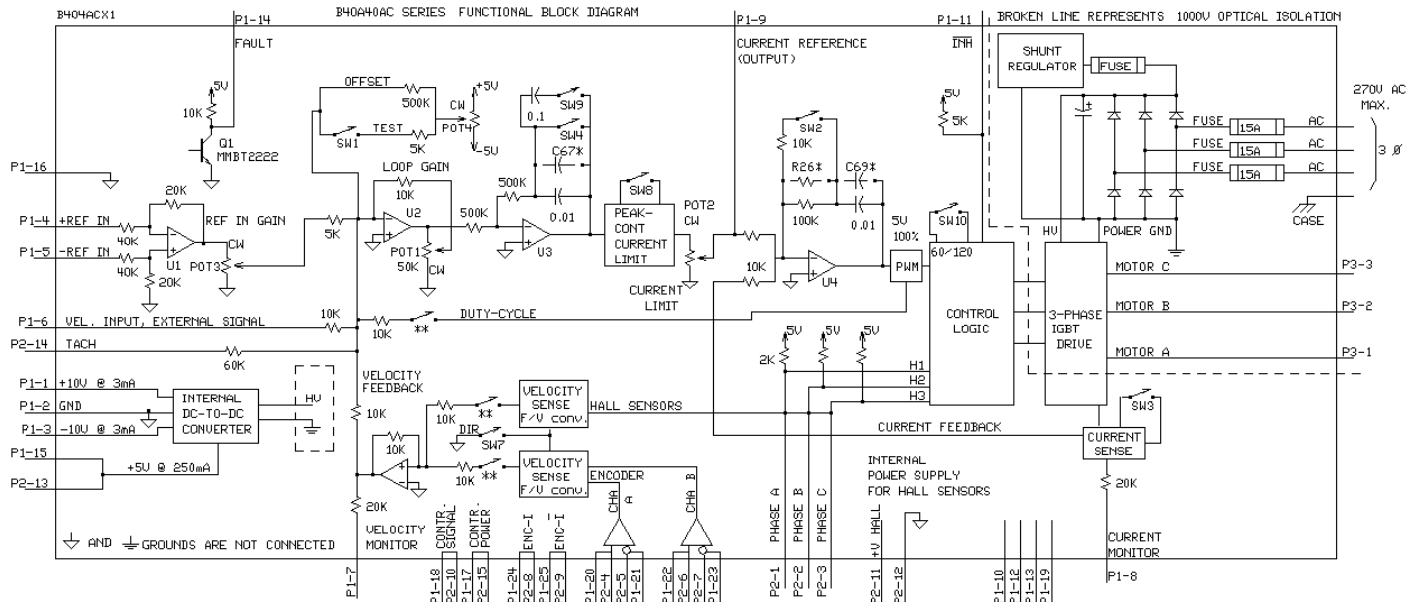
FEEDBACK SUPPORTED

- Halls
- Incremental Encoder
- Tachometer
- ± 10 V Analog

COMPLIANCES & AGENCY APPROVALS

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS

BLOCK DIAGRAM



MODE SELECTION

| | SW2 | SW4 | SW5 | SW6 | ENC | TACH |
|-------------------|-----|-----|-----|-----|------|------|
| CURRENT MODE | ON | ON | OFF | OFF | NC | NC |
| HALL VELOCITY | ON | OFF | OFF | ON | NC | NC |
| ENCODER VELOCITY | ON | OFF | ON | ON | CONN | NC |
| OPEN LOOP MODE | ON | OFF | ON | OFF | NC | NC |
| EXTERNAL VELOCITY | ON | OFF | OFF | OFF | NC | CONN |

NC=NOT CONNECTED, CONN=CONNECTED

LED GREEN - NORMAL OPERATION, LED RED- FAULT
 RECOMMENDED SETTING FOR CURRENT MODE - POT1 FULLY CCW, POT3 FULLY CW
 AMPLIFIERS ARE SHIPPED IN CURRENT MODE WITH MAXIMUM CURRENT SETTINGS
 SW9 MUST BE ON FOR PROPER OPERATION IN HALL VELOCITY MODE
 FOR OTHER SWITCH FUNCTIONS SEE SWITCH DESCRIPTION
 * OPTIONAL USER INSTALLED THROUGH HOLE COMPONENTS
 ** THESE MODE FUNCTIONS ARE CONTROLLED BY COMBINATIONS OF SW5 AND SW6.

Information on Approvals and Compliances*



US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.



Compliant with European CE for both the Class A EMC Directive 89/336/EEC on Electromagnetic Compatibility (specifically EN 61000-6-4:2001, EN 61000-6-2:2001, EN 61000-3-2:2000, and EN 61000-3-3:1995/A1:2001) and LVD requirements of directive 73/23/EEC (specifically EN 60204-1), a low voltage directive to protect users from electrical shock.



RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.

*Approvals may be pending. See "Compliances & Agency Approvals" on page 1 of datasheet for currently held approvals.

SPECIFICATIONS

| Power Specifications | | |
|---|---------|--|
| Description | Units | Value |
| AC Supply Voltage Range | VAC | 45 - 270 |
| AC Supply Frequency | Hz | 50 - 60 |
| DC Bus Over Voltage Limit | VDC | 420 |
| Maximum Peak Output Current ¹ | A | 40 |
| Maximum Continuous Output Current | A | 20 |
| Maximum Power Dissipation at Continuous Current | W | 380 |
| Internal Bus Capacitance | µF | 2970 |
| Internal Shunt Resistance | Ω | 20 |
| Internal Shunt Resistor Power Rating | W | 100 |
| Internal Shunt Resistor Turn-on Voltage | VDC | 390 |
| Minimum Load Inductance (Line-To-Line) ² | µH | 600 |
| Switching Frequency | kHz | 20 |
| Shunt Fuse | A | 3 |
| Bus Fuse | A | 15 |
| Control Specifications | | |
| Description | Units | Value |
| Command Sources | - | ±10 V Analog |
| Feedback Supported | - | ±10 V Analog, Halls, Incremental Encoder, Tachometer |
| Commutation Methods | - | Trapezoidal |
| Modes of Operation | - | Current, Encoder Velocity, External/Analog Velocity, Hall Velocity, Open Loop, Tachometer Velocity |
| Motors Supported | - | Brushed, Brushless, Voice Coil |
| Hardware Protection | - | Invalid Commutation Feedback, Over Current, Over Temperature, Over Voltage, Short Circuit (Phase-Phase & Phase-Ground) |
| Internal Shunt Regulator | - | Yes |
| Internal Shunt Resistor | - | Yes |
| Mechanical Specifications | | |
| Description | Units | Value |
| Agency Approvals | - | CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL |
| Size (H x W x D) | mm (in) | 234.7 x 163.7 x 114.2 (9.2 x 6.4 x 4.5) |
| Weight | g (oz) | 3100 (109.3) |
| Heatsink (Base) Temperature Range ³ | °C (°F) | 0 - 65 (32 - 149) |
| Storage Temperature Range | °C (°F) | -40 - 85 (-40 - 185) |
| Form Factor | - | Stand Alone |
| P1 Connector | - | 25-pin, female D-sub |
| P2 Connector | - | 15-pin, female D-sub |
| P3 Connector | - | 3-contact, 11.10 mm spaced, tri-barrier terminal block |
| P4 Connector | - | 4-contact, 11.10 mm spaced, tri-barrier terminal block |

Notes

1. Maximum duration of peak current is ~2 seconds.
2. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
3. Additional cooling and/or heatsink may be required to achieve rated performance.

PIN FUNCTIONS

| P1 - Signal Connector | | | |
|-----------------------|------------------|--|------|
| Pin | Name | Description / Notes | I/O |
| 1 | +10V 3mA OUT | ±10 V @ 3 mA low power supply for customer use. Short circuit protected. Reference ground common with signal ground. | O |
| 2 | SIGNAL GND | | SGND |
| 3 | -10V 3mA OUT | | O |
| 4 | +REF IN | Differential Reference Input (±10 V Operating Range, ±15 V Maximum Input) | I |
| 5 | -REF IN | | I |
| 6 | VEL INPUT | Single ended reference input for external velocity signal, range ±10 V (maximum ±15 V). | I |
| 7 | VEL MONITOR OUT | Velocity Monitor. Analog output proportional to motor speed. In Encoder Velocity mode, output is proportional to the encoder line frequency. In Hall Velocity mode, output is proportional to the electrical cycle frequency. Encoder Velocity scaling is 25 kHz/V. Hall Velocity scaling is 100 Hz/V. | O |
| 8 | CURR MONITOR OUT | Current Monitor. Analog output signal proportional to the actual current output. Scaling is 5.7 A/V by default but may be reduced by DIP switch settings (see Hardware Settings section below). Measure relative to signal ground. | O |
| 9 | CURR REF OUT | Measures the command signal to the internal current-loop. This pin has a maximum output of ±7.25 V when the drive outputs maximum peak current. Measure relative to signal ground. | O |
| 10 | RESERVED | Reserved | - |
| 11 | INHIBIT IN | TTL level (+5 V) inhibit/enable input. Leave open to enable drive. Pull to ground to inhibit drive. Inhibit turns off all power devices. | I |
| 12 | RESERVED | Reserved | - |
| 13 | RESERVED | Reserved | - |
| 14 | FAULT OUT | TTL level (+5 V) output becomes high when power devices are disabled due to at least one of the following conditions: inhibit, invalid Hall state, output short circuit, over voltage, over temperature, power-up reset. | O |
| 15 | +5V @ 250mA | ±5 V @ 250 mA low power supply for customer use. Short circuit protected. Referenced to signal ground. | O |
| 16 | SIGNAL GND | Signal Ground | SGND |
| 17 | CTLR POWER | Controller Power. Pass-through to Port 2 (P2) for customer use. | I/O |
| 18 | CTLR SIGNAL | User Controller Signal. Pass-through to Port 2 (P2) for customer use. | I/O |
| 19 | RESERVED | Reserved | - |
| 20 | ENC CH A+ | Differential Encoder Channel A Output. Pass-through from Port 2 (P2). | O |
| 21 | ENC CH A- | | O |
| 22 | ENC CH B+ | Differential Encoder Channel B Output. Pass-through from Port 2 (P2). | O |
| 23 | ENC CH B- | | O |
| 24 | INDEX+ | Differential Encoder Index Output. Pass-through from Port 2 (P2). | O |
| 25 | INDEX- | | O |

| P2 - Feedback Connector | | | |
|-------------------------|-------------|---|------|
| Pin | Name | Description / Notes | I/O |
| 1 | HALL 1 | Single-ended Hall/Commutation Sensor Inputs (+5 V logic level) | I |
| 2 | HALL 2 | | I |
| 3 | HALL 3 | | I |
| 4 | ENC. CH. A+ | Differential Encoder Channel A Input (+5 V Logic Level) | I |
| 5 | ENC. CH. A- | | I |
| 6 | ENC. CH. B+ | Differential Encoder Channel B Input (+5 V Logic Level) | I |
| 7 | ENC. CH. B- | | I |
| 8 | INDEX+ | Differential Encoder Index Input (+5 V Logic Level) | I |
| 9 | INDEX- | | I |
| 10 | CTLR SIGNAL | User Controller Signal. Pass-through to Port 1 (P1) for customer use. | I/O |
| 11 | +V HALL OUT | Low Power Supply For Hall Sensors (+6 V @ 30 mA). Referenced to signal ground. Short circuit protected. | O |
| 12 | GND | Signal Ground | SGND |
| 13 | +5V @ 250mA | ±5 V @ 250 mA low power supply for customer use. Short circuit protected. Referenced to signal ground. | O |
| 14 | TACH | Negative Tachometer Input (Maximum ±60 V). Use signal ground for positive input. | I |
| 15 | CTLR POWER | Controller Power. Pass-through to Port 1 (P1) for customer use. | I/O |

| P3 - Motor Power Connector | | | |
|----------------------------|---------|---------------------|-----|
| Pin | Name | Description / Notes | I/O |
| 1 | MOTOR A | Motor Phase A | O |
| 2 | MOTOR B | Motor Phase B | O |
| 3 | MOTOR C | Motor Phase C | O |

P4 - AC Power Connector

| Pin | Name | Description / Notes | I/O |
|-----|----------|---|-----|
| 1 | AC1 | AC Supply Input (Single Or Three Phase) | I |
| 2 | AC2 | | I |
| 3 | AC3 | | I |
| 4 | CASE GND | Case Ground | PE |

HARDWARE SETTINGS
Switch Functions

| Switch | Description | Setting | |
|--------|---|------------------------|------------------------|
| | | On | Off |
| 1 | Test/Offset. Switches the function of the Test/Offset pot between an on-board command input for testing or a command offset adjustment. OFF by default. | Test | Offset |
| 2 | Current loop proportional gain adjustment. ON by default. | Decrease | Increase |
| 3 | Current scaling. When OFF, increases sensitivity of current sense thus reducing both peak and continuous current limit by 50%. The scaling of the current monitor output signal becomes ½ its ordinary value when this switch is OFF. | Full-current | Half-current |
| 4 | Outer loop integration. Activates or deactivates integration. ON, by default, for current mode and OFF for other modes. | Inactive | Active |
| 5 | Mode selection. See mode selection table below. | - | - |
| 6 | Mode selection. See mode selection table below. | - | - |
| 7 | Velocity feedback polarity. Changes the polarity of the internal feedback signal and the velocity monitor output signal. Inversion of the feedback polarity may be required to prevent a motor run-away condition. | Standard | Inverted |
| 8 | Current ratio. Used to set continuous-to-peak current ratio. Default is ON. | Cont./Peak Ratio = 50% | Cont./Peak Ratio = 25% |
| 9 | Outer loop integral gain adjustment. It is recommended to leave this switch OFF for most applications, but ON for Hall Velocity Mode. | Decrease | Increase |
| 10 | Hall sensor phasing. Selects 120°/60° commutation phasing. ON by default. | 120° | 60° |

Mode Selection Table

| | SW4 | SW5 | SW6 | Encoder | Tachometer |
|---------------------|-----|-----|-----|---------------|---------------|
| CURRENT | ON | OFF | OFF | Not Connected | Not Connected |
| OPEN LOOP | OFF | ON | OFF | Not Connected | Not Connected |
| HALL VELOCITY* | OFF | OFF | ON | Not Connected | Not Connected |
| ENCODER VELOCITY* | OFF | ON | ON | Connected | Not Connected |
| TACHOMETER VELOCITY | OFF | OFF | OFF | Not Connected | Connected |
| EXTERNAL VELOCITY | OFF | OFF | OFF | Not Connected | Not Connected |

*NOTE: See details of switch 7 for further Hall/Encoder Velocity configuration information.

Potentiometer Functions

| Potentiometer | Description | Turning CW |
|---------------|--|--------------------------------------|
| 1 | Loop gain adjustment for voltage/velocity modes. Turn this pot fully CCW in current mode. | Increases gain |
| 2 | Current limit. It adjusts both continuous and peak current limit while maintaining their ratio. | Increases limit |
| 3 | Reference gain. Adjusts the ratio between input signal and output variables (voltage, current, or velocity). | Increases gain |
| 4 | Offset / Test. Used to adjust any imbalance in the input signal or in the amplifier. Can also be used as an on-board signal source for testing purposes. | Adjusts offset in negative direction |

Note: Potentiometers are approximately linear and have 12 active turns with 1 inactive turn on each end.

Through-hole Components[†]

| Location | Description |
|----------|--|
| C67* | Velocity Loop Integrator. Through-hole capacitor that can be added for more precise velocity loop tuning. See section below on Tuning with Through-hole components for more details. |
| C69* | Current Loop Integrator. Through-hole capacitor that can be added for more precise current loop tuning. See section below on Tuning with Through-hole components for more details. |
| R26* | Current Loop Proportional Gain. Through-hole resistor that can be added for more precise current loop tuning. See section below on Tuning with Through-hole components for more details. |

Tuning With Through-hole Components

In general, the drive will not need to be further tuned with through-hole components. However, for applications requiring more precise tuning than what is offered by the potentiometers and dipswitches, the drive can be manually modified with through-hole resistors and capacitors as denoted in the above table. By default, the through-hole locations are not populated when the drive is shipped. Before attempting to add through-hole components to the board, consult the section on loop tuning in the installation notes on the manufacturer's website. Some general rules of thumb to follow when adding through-hole components are:

- A larger resistor value will increase the proportional gain, and therefore create a faster response time.
- A larger capacitor value will increase the integration time, and therefore create a slower response time.

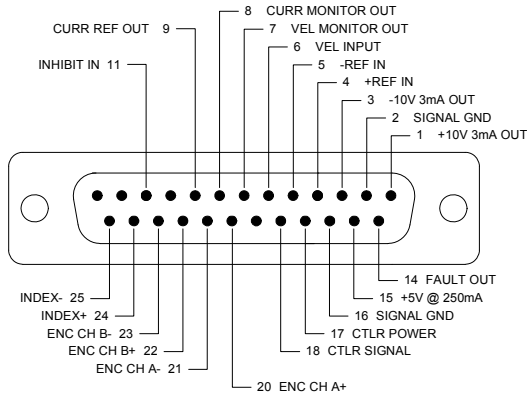
Proper tuning using the through-hole components will require careful observation of the loop response on a digital oscilloscope to find the optimal through-hole component values for the specific application.

[†]Note: Damage done to the drive while performing these modifications will void the warranty.

MECHANICAL INFORMATION

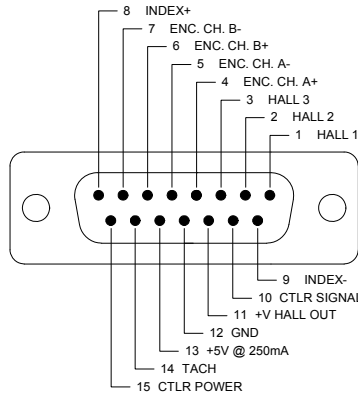
P1 - Signal Connector

| | | |
|-----------------------|---------------------|--|
| Connector Information | | 25-pin, female D-sub |
| Mating Connector | Details | AMP: Plug P/N 205204-4; Housing P/N 748677-1; Terminals P/N 5-66507-7 (loose) or 3-66507-0 (strip) |
| | Included with Drive | No |



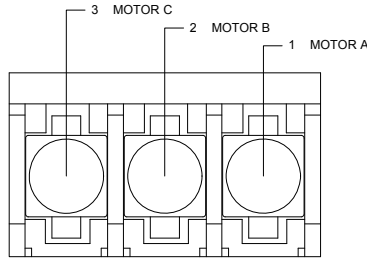
P2 - Feedback Connector

| | | |
|-----------------------|---------------------|--|
| Connector Information | | 15-pin, female D-sub |
| Mating Connector | Details | AMP: Plug P/N 205204-4; Housing P/N 748677-1; Terminals P/N 5-66507-7 (loose) or 3-66507-0 (strip) |
| | Included with Drive | No |



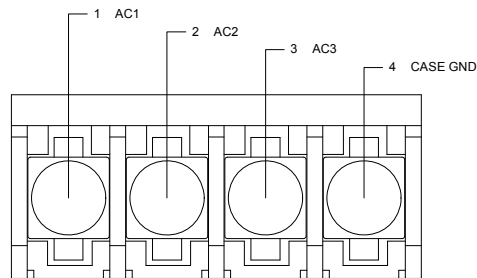
P3 - Motor Power Connector

| | | |
|-----------------------|---------------------|--|
| Connector Information | | 3-contact, 11.10 mm spaced, tri-barrier terminal block |
| Mating Connector | Details | Not applicable |
| | Included with Drive | Not applicable |

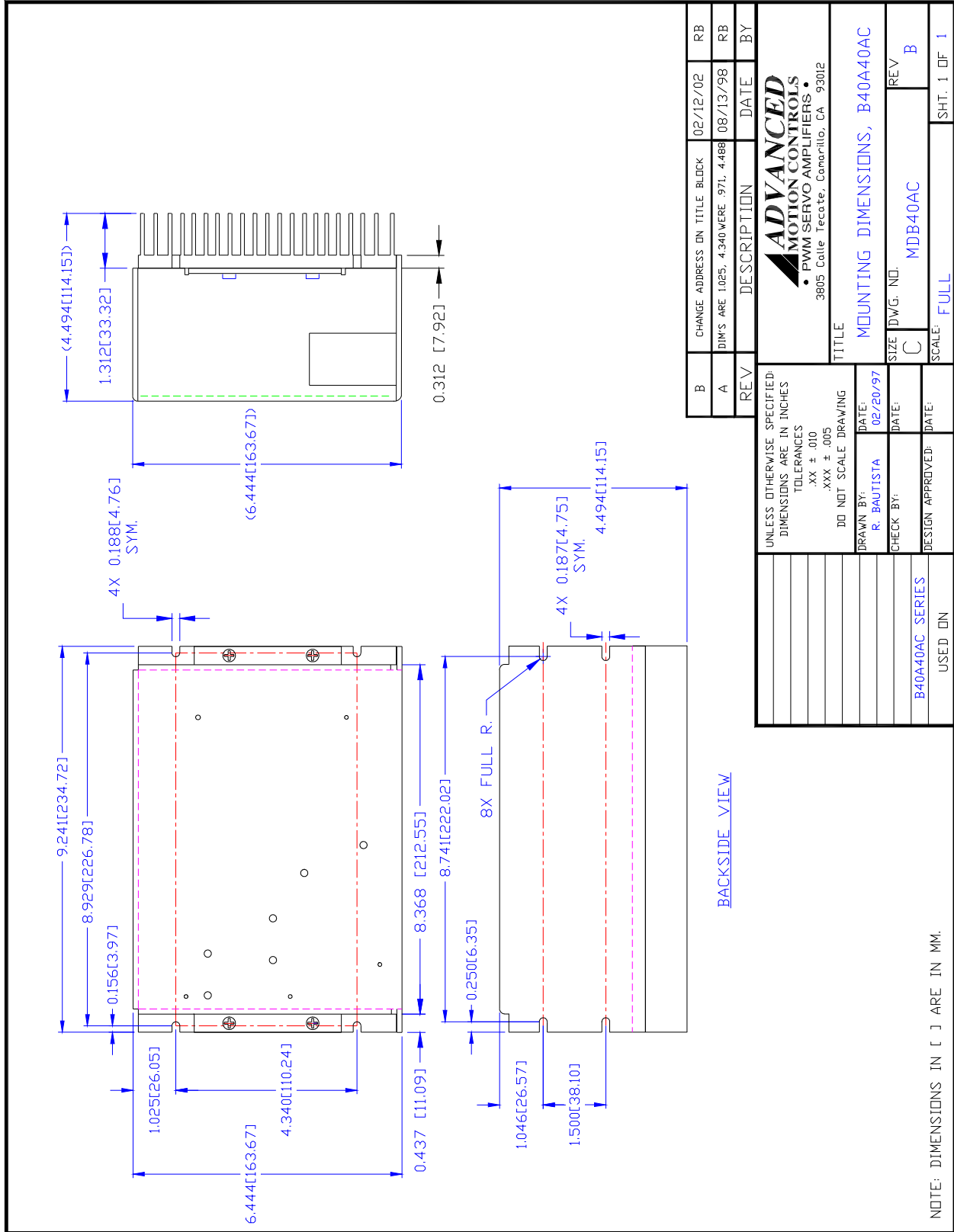


P4 - AC Power Connector

| | | |
|-----------------------|---------------------|--|
| Connector Information | | 4-contact, 11.10 mm spaced, tri-barrier terminal block |
| Mating Connector | Details | Not applicable |
| | Included with Drive | Not applicable |



MOUNTING DIMENSIONS



| | | | |
|-----|--|----------|----|
| B | CHANGE ADDRESS ON TITLE BLOCK | 02/12/02 | RB |
| A | DIMS ARE 1.025, 4.340 WERE .971, 4.468 | 08/13/98 | RB |
| REV | DESCRIPTION | DATE | BY |

ADVANCED
MOTION CONTROLS
• PWM SERVO AMPLIFIERS •
3805 Calle Tecate, Camarillo, CA 93012

TITLE
MOUNTING DIMENSIONS, B40A40AC

SIZE DWG. NO. MDB40AC
SCALE FULL

REV B

SHT. 1 OF 1

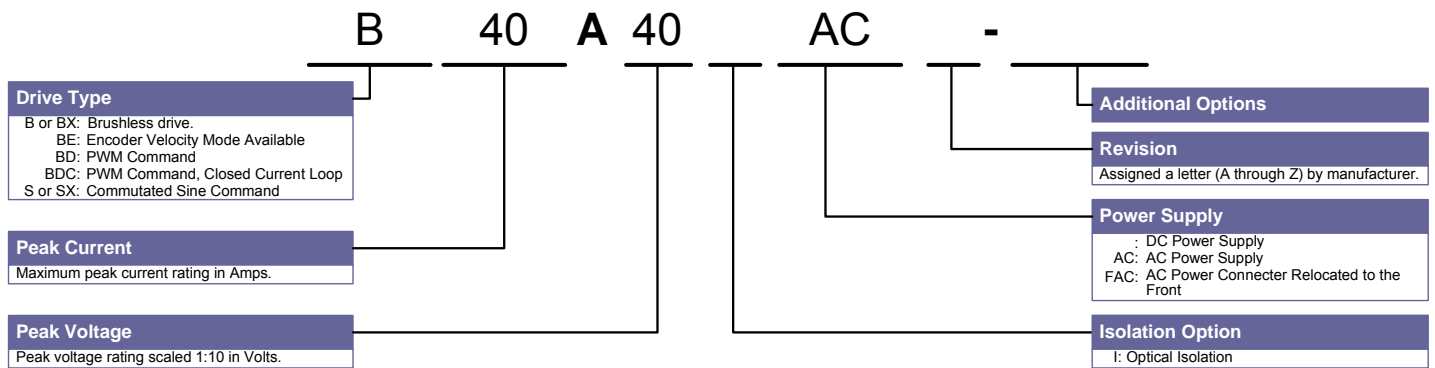
UNLESS OTHERWISE SPECIFIED:
DIMENSIONS ARE IN INCHES
TOLERANCES
.XX ± .010
.XXX ± .005
DO NOT SCALE DRAWING

DRAWN BY: R. BAUTISTA
DATE: 02/20/97

CHECK BY:
DATE:

DESIGN APPROVED:
DATE:

B40A40AC - SERIES
USED ON

PART NUMBERING INFORMATION


All analog servo drive models listed in the selection tables of the website are readily available, standard product offerings. However, additional features and/or options are available for select drives and other possibilities can be made available for OEMs with sufficient volume requests. Feel free to contact Applications Engineering for further information and details.

All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.