

### Description

The BD15A8 PWM servo drive is designed to drive brushless DC motors at a high switching frequency. It is fully protected against over-voltage, over-current, over-heating and short-circuits. The drive interfaces with digital controllers that have a digital PWM output. PWM IN determines the output duty cycle. DIR IN determines the direction of rotation. A single red/green LED indicates operating status. The current limit can be set by DIP switches.

See Part Numbering Information on last page of datasheet for additional ordering options.

Power Range	
Peak Current	15 A
Continuous Current	7.5 A
Supply Voltage	20 - 80 VDC



#### **Features**

- ▲ Four Quadrant Regenerative Operation
- Optically Isolated Digital Inputs
- ▲ Adjustable Current Limits
- High Switching Frequency

- Digital Fault Output Monitor
- ▲ Selectable 120/60 Hall Commutation Phasing
- Drive Status LED

# MODES OF OPERATION

Direct PWM

### COMMAND SOURCE

PWM and Direction

### FEEDBACK SUPPORTED

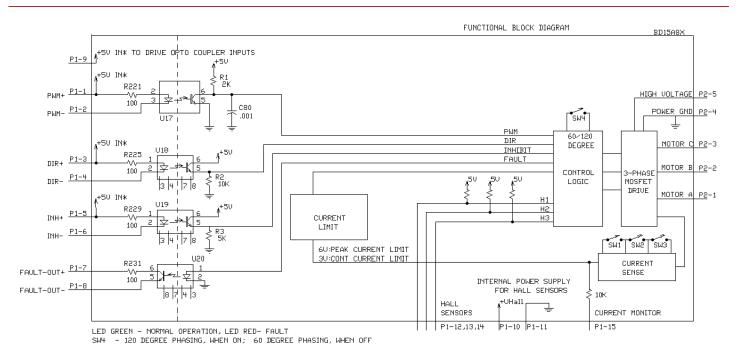
Halls

### **COMPLIANCES & AGENCY APPROVALS**

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS



### **BLOCK DIAGRAM**



	Information on Approvals and Compliances				
c <b>FL</b> °us	US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.				
(€	Compliant with European CE for both the Class A EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 and EN 61000-6-2:2005) and LVD requirements of directive 2006/95/EC (specifically EN 60204-1:2006), a low voltage directive to protect users from electrical shock.				
COMPLIANCE	RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.				



## **SPECIFICATIONS**

Power Specifications			
Description Description	Units VDC	Value	
DC Supply Voltage Range	VDC	20 - 80 85	
DC Bus Over Voltage Limit	-		
Maximum Peak Output Current <sup>1</sup>	A	15	
Maximum Continuous Output Current	A	7.5	
Maximum Continuous Output Power	W	570	
Maximum Power Dissipation at Continuous Current	W	30	
Minimum Load Inductance (Line-To-Line) <sup>2</sup>	μH	200	
Low Voltage Supply Outputs	-	±6 VDC (3 mA)	
Switching Frequency Range	kHz	5 - 20	
		pecifications	
Description	Units	Value	
Command Sources	-	PWM and Direction	
Feedback Supported	-	Halls	
Commutation Methods	-	Trapezoidal	
Modes of Operation	-	Direct PWM	
Motors Supported	-	Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)	
Hardware Protection	-	Invalid Commutation Feedback, Over Current, Over Temperature, Over Voltage, Short Circuit (Phase-Phase & Phase-Ground)	
Primary I/O Logic Level	-	5V TTL	
	Mechanical	Specifications	
Description	Units	Value	
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL	
Size (H x W x D)	mm (in)	129.3 x 75.8 x 25.1 (5.1 x 3 x 1)	
Weight	g (oz)	280 (9.9)	
Heatsink (Base) Temperature Range <sup>3</sup>	°C (°F)	0 - 65 (32 - 149)	
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)	
Form Factor	-	Panel Mount	
P1 Connector	-	16-pin, 2.54 mm spaced, friction lock header	
P2 Connector	-	5-port, 5.08 mm spaced, screw terminal	

### Notes

- Maximum duration of peak current is ~2 seconds. Peak RMS value must not exceed continuous current rating of the drive. 1.
- Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements. Additional cooling and/or heatsink may be required to achieve rated performance. 2. 3.



# **PIN FUNCTIONS**

	P1 - Signal Connector			
Pin	Name	Description / Notes	1/0	
1	+PWM	Opto-isolated Pulse Width Modulation Input. Positive input internally connected to P1-9.	I	
2	-PWM	Ground negative input to activate. Activating opto-couple activates bridge output.	I	
3	+DIR	Opto-isolated Direction Input. Positive input internally connected to P1-9. Ground negative	I	
4	-DIR	input to activate. Activating opto-couple activates bridge output.	I	
5	+INHIBIT	Opto-isolated Inhibit Input. Positive input internally connected to P1-9. Ground negative	I	
6	-INHIBIT	input to activate. Activating opto-couple activates bridge output.	I	
7	+FAULT	Opto-isolated Fault Output (+5 V). Output transistor turns on during output short circuit,		
8	-FAULT	over voltage, over temperature, inhibit, invalid Hall state, and during power-up reset. Fault condition indicated by red LED.	0	
9	+5V IN	+5 V (at least 150 mA) input to drive opto-isolated inputs.	I	
10	+V HALL OUT	Low Power Supply For Hall Sensors (+6 V @ 30 mA). Short circuit protected.	0	
11	GND	Low I ower supply I of Hall defisors (40 V @ 30 MA). Short dictal protected.	GND	
12	HALL 1		I	
13	HALL 2	Single-ended Hall/Commutation Sensor Inputs (+5 V logic level)	I	
14	HALL 3			
15	CURR MONITOR OUT  A/V by default but may be reduced by DIP switch settings (see Hardware Settings section below). Measure relative to power ground.		0	
16	NC	Not Connected (Reserved)	-	

	P2 - Power Connector			
Pin	Name	Description / Notes	1/0	
1	MOTOR A	Motor Phase A	0	
2	MOTOR B	Motor Phase B	0	
3	MOTOR C	Motor Phase C	0	
4	POWER GND	Power Ground (Isolated From Signal Ground)	PGND	
5	HIGH VOLTAGE	DC Power Input	I	



## HARDWARE SETTINGS

## **Switch Functions**

Switch	Description	Setting		
		On	Off	
1	Bit 0 of the current limit setting. See details below.	1	0	
2	Bit 1 of the current limit setting. See details below.	1	0	
3	3 Bit 2 of the current limit setting. See details below.		0	
4	60/120 degree commutation phasing setting	120 degrees	60 degrees	

### Additional Details

Switches 1, 2 and 3 can be used to reduce the peak and continuous current limit to a percentage given in the table below. 100% means no reduction.

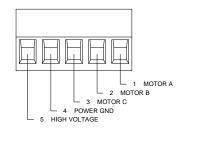
Current Limit %	Current Monitor Scaling (A/V)	Switch Setting		
		Switch 3	Switch 2	Switch 1
12.5	0.25	OFF	OFF	OFF
25	0.5	OFF	OFF	ON
50	1	OFF	ON	ON
100	2	ON	ON	ON



## **MECHANICAL INFORMATION**

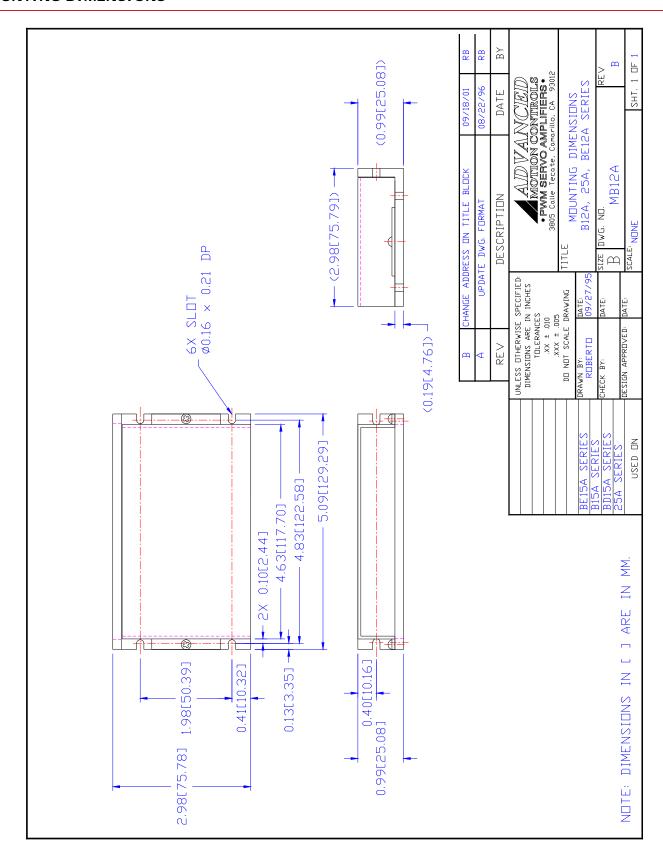
		P1 - Signal Connector
Connector Information		16-pin, 2.54 mm spaced, friction lock header
Mating Connector	Details	Molex: P/N 22-01-3167 (connector) and P/N 08-50-0114 (insert terminals)
Mating Connector	Included with Drive	Yes
		15 CURR MONITOR OUT  13 HALL 2  11 GND  9 +5V IN  7 +FAULT  5 +INHIBIT  5 +INHIBIT  6 -INHIBIT  10 +V HALL OUT  14 HALL 3  16 NC

P2 - Power Connector		
Connector Information		5-port, 5.08 mm spaced, screw terminal
Moting Connector	Details	Not applicable
Mating Connector	Included with Drive	Not applicable



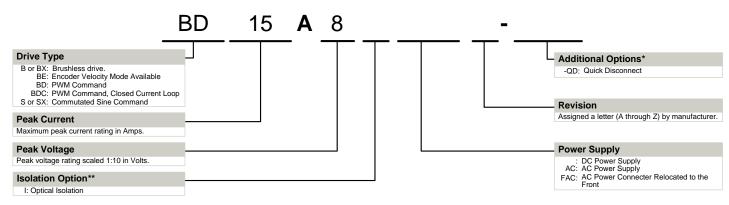


# MOUNTING DIMENSIONS





## PART NUMBERING INFORMATION



<sup>\*</sup> Options available for orders with sufficient volume. Contact ADVANCED Motion Controls for more information.

ADVANCED Motion Controls analog series of servo drives are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

#### **Examples of Modifications and Customized Products**

- ▲ Integration of Drive into Motor Housing
- ▲ Mount OEM PCB onto Drive Without Cables
- ▲ Multi-axis Configuration for Compact System
- Custom PCB and Baseplate for Optimized Footprint
- ▲ RTV/Epoxy Components for High Vibration
- ▲ OEM Specified Connectors for Instant Compatibility
- ▲ OEM Specified Silkscreen for Custom Appearance
- ▲ Increased Thermal Limits for High Temp. Operation
- ▲ Integrate OEM Circuitry onto Drive PCB
- Custom Control Loop Tuned to Motor Characteristics

- ▲ Optimized Switching Frequency
- ▲ Ramped Velocity Command for Smooth Acceleration
- Remove Unused Features to Reduce OEM Cost
- ▲ Application Specific Current and Voltage Limits

Feel free to contact Applications Engineering for further information and details.

# **Available Accessories**

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit <a href="https://www.a-m-c.com">www.a-m-c.com</a> to see which accessories will assist with your application design and implementation.



All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.

Release Date: 11/30/2011

<sup>\*\*</sup> İsolation comes standard on all AC supply drives and most DC supply drives 200V and above. Consult selection tables of the website or drive datasheet block diagram to see if isolation is included.