

**Description**

The DigiFlex® Performance™ (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The command source can be generated internally or can be supplied externally. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a CANopen interface for networking and a RS-232 interface for drive configuration and setup. Drive commissioning is accomplished using DriveWare, available at [www.a-m-c.com](http://www.a-m-c.com).

All drive and motor parameters are stored in non-volatile memory.

**Power Range**

Peak Current	100 A (70.7 A <sub>RMS</sub> )
Continuous Current	50 A (35.4 A <sub>RMS</sub> )
Supply Voltage	200 - 240 VAC



**Features**

- ▲ Four Quadrant Regenerative Operation
- ▲ Space Vector Modulation (SVM) Technology
- ▲ Fully Digital State-of-the-art Design
- ▲ Programmable Gain Settings
- ▲ Fully Configurable Current, Voltage, Velocity and Position Limits
- ▲ PIDF Velocity Loop
- ▲ PID + FF Position Loop
- ▲ Compact Size, High Power Density
- ▲ 16-bit Analog to Digital Hardware
- ▲ Built-in brake/shunt regulator

**MODES OF OPERATION**

- Current
- Position
- Velocity

**COMMAND SOURCE**

- ±10 V Analog
- PWM and Direction
- Encoder Following
- Over the Network

**FEEDBACK SUPPORTED**

- Halls
- Incremental Encoder
- Auxiliary Incremental Encoder
- Tachometer (±10 VDC)

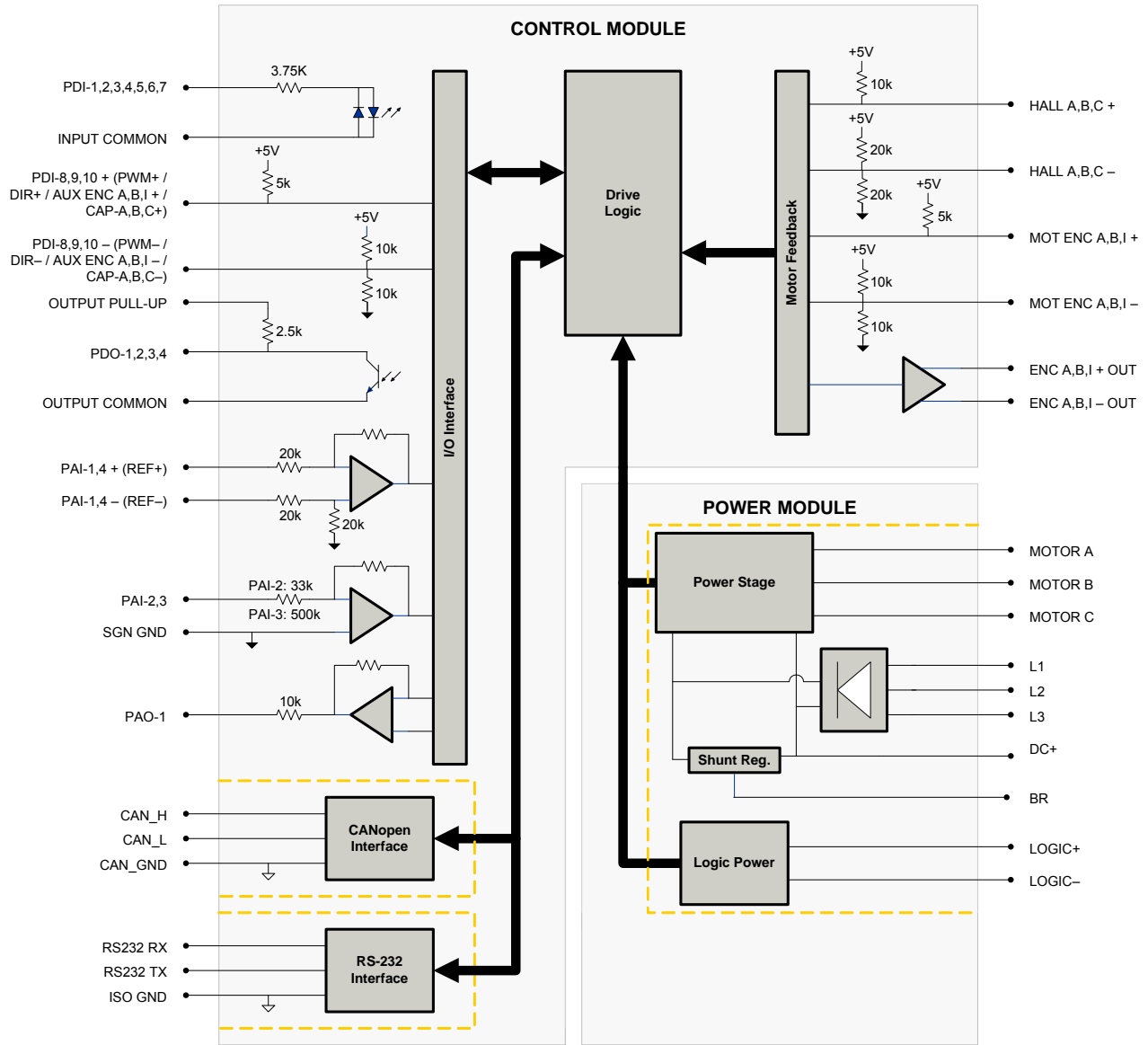
**INPUTS/OUTPUTS**

- 3 High Speed Captures
- 4 Programmable Analog Inputs (16-bit/12-bit Resolution)
- 1 Programmable Analog Output (10-bit Resolution)
- 3 Programmable Digital Inputs (Differential)
- 7 Programmable Digital Inputs (Single-Ended)
- 4 Programmable Digital Outputs (Single-Ended)

**COMPLIANCES & AGENCY APPROVALS**

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS

**BLOCK DIAGRAM**



**Information on Approvals and Compliances**



US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.



Compliant with European CE for both the Class A EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 and EN 61000-6-2:2005) and LVD requirements of directive 2006/95/EC (specifically EN 60204-1:2006), a low voltage directive to protect users from electrical shock.



RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.

**SPECIFICATIONS**

Power Specifications		
Description	Units	Value
Rated Voltage	VAC (VDC)	240 (339)
AC Supply Voltage Range	VAC	200 - 240
AC Supply Minimum	VAC	180
AC Supply Maximum	VAC	264
AC Input Phases <sup>1</sup>	-	3
AC Supply Frequency	Hz	50 - 60
DC Supply Voltage Range <sup>2</sup>	VDC	255 - 373
DC Bus Over Voltage Limit	VDC	429
DC Bus Under Voltage Limit	VDC	205
Logic Supply Voltage	VDC	20 - 30 (@ 850 mA maximum)
Maximum Peak Output Current <sup>3</sup>	A (Arms)	100 (70.7)
Maximum Continuous Output Current	A (Arms)	50 (35.4)
Max. Continuous Output Power @ Rated Voltage <sup>4</sup>	W	11400
Max. Continuous Power Dissipation @ Rated Voltage	W	600
Internal Bus Capacitance	µF	1500
External Shunt Resistor Minimum Resistance <sup>5</sup>	Ω	10
Minimum Load Inductance (Line-To-Line) <sup>6</sup>	µH	600
Switching Frequency	kHz	16
Maximum Output PWM Duty Cycle	%	100
Low Voltage Supply Outputs	-	+5 VDC (250 mA)
Control Specifications		
Description	Units	Value
Communication Interfaces	-	CANopen (RS-232 for configuration)
Command Sources	-	±10 V Analog, Encoder Following, Over the Network, PWM and Direction
Feedback Supported	-	Auxiliary Incremental Encoder, Halls, Incremental Encoder, Tachometer (±10 VDC)
Commutation Methods	-	Sinusoidal, Trapezoidal
Modes of Operation	-	Current, Position, Velocity
Motors Supported	-	Closed Loop Vector, Single Phase (Brushed, Voice Coil, Inductive Load), Three Phase (Brushless)
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	10/4
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	4/1
Primary I/O Logic Level	-	24 VDC
Current Loop Sample Time	µs	62.5
Velocity Loop Sample Time	µs	125
Position Loop Sample Time	µs	125
Maximum Encoder Frequency	MHz	20 (5 pre-quadrature)
Internal Shunt Regulator	-	Yes
Internal Shunt Resistor	-	No
Mechanical Specifications		
Description	Units	Value
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL
Size (H x W x D)	mm (in)	272.8 x 230.4 x 149.4 (10.7 x 9.1 x 5.9)
Weight	g (oz)	5500 (194)
Heatsink (Base) Temperature Range <sup>7</sup>	°C (°F)	0 - 75 (32 - 167)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Form Factor	-	Panel Mount
Cooling System	-	Forced Convection
IP Rating	-	IP10
AUX COMM Connector	-	3-pin, 2.5 mm spaced, enclosed, friction lock header
AUX ENCODER Connector	-	15-pin, high-density, male D-sub
BRAKE/LOGIC Connector	-	4-contact, 13 mm spaced, dual-barrier terminal block
COMM Connector	-	Shielded, dual RJ-45 socket with LEDs
FEEDBACK Connector	-	15-pin, high-density, female D-sub
I/O Connector	-	26-pin, high-density, female D-sub
MOTOR POWER Connector	-	4-contact, 13 mm spaced, dual-barrier terminal block
POWER Connector	-	4-contact, 13 mm spaced, dual-barrier terminal block

**Notes**

1. Can operate on single-phase VAC if peak/cont. current ratings are reduced by at least 30%.
2. DC Supply operation will reduce peak/cont. current ratings by at least 30%.
3. Capable of supplying drive rated peak current for 2 seconds with 10 second foldback to continuous value. Longer times are possible with lower current limits.
4.  $P = (\text{DC Rated Voltage}) * (\text{Cont. RMS Current}) * 0.95$ .
5. *ADVANCED* Motion Controls recommends using an external fuse in series with the shunt resistor. A 3 amp motor delay fuse is typical.
6. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
7. Additional cooling and/or heatsink may be required to achieve rated performance.

**PIN FUNCTIONS**

<b>AUX COMM - RS232 Communication Connector</b>			
Pin	Name	Description / Notes	I/O
1	RS232 RX	Receive Line (RS-232)	I
2	RS232 TX	Transmit Line (RS-232)	O
3	ISO GND	Isolated Signal Ground	IGND

<b>AUX ENCODER - Auxiliary Feedback Connector</b>			
Pin	Name	Description / Notes	I/O
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	PDI-8 + (PWM+ / AUX ENC A+ / CAP-B+)	Programmable Digital Input or PWM or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
5	PDI-8 - (PWM- / AUX ENC A- / CAP-B-)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
6	PDI-9 + (DIR+ / AUX ENC B+ / CAP-C+)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
7	PDI-9 - (DIR- / AUX ENC B- / CAP-C-)	Programmable Digital Input or Direction Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
8	PDI-10 + (AUX ENC I+ / CAP-A+)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
9	PDI-10 - (AUX ENC I- / CAP-A-)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture (For Single-Ended Signals Leave Negative Terminal Open)	I
10	SGN GND	Signal Ground	SGND
11	SGN GND	Signal Ground	SGND
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-4 +	Differential Programmable Analog Input (12-bit Resolution)	I
15	PAI-4 -		I

<b>BRAKE/LOGIC - Logic Power Connector</b>			
Pin	Name	Description / Notes	I/O
1	LOGIC GND	Logic Supply Ground	GND
2	LOGIC PWR	Logic Supply Input	I
3	BR	External Brake Resistor Connection	-
4	DC+	Brake Resistor DC+. Connection for brake resistor.	O

<b>COMM - CAN Communication Connector</b>			
Pin	Name	Description / Notes	I/O
1	CAN_H	CAN_H Line (Dominant High)	I
2	CAN_L	CAN_L Line (Dominant Low)	I
3	CAN_GND	CAN Ground	CGND
4	RESERVED	Reserved	-
5	RESERVED	Reserved	-
6	RESERVED	Reserved	-
7	CAN_GND	CAN Ground	CGND
8	RESERVED	Reserved	-

<b>FEEDBACK - Feedback Connector</b>			
Pin	Name	Description / Notes	I/O
1	HALL A+	Commutation Sensor Inputs	I
2	HALL B+		I
3	HALL C+		I
4	MOT ENC A+	Differential Encoder A Channel Input (For Single Ended Signals Use Only The Positive Input)	I
5	MOT ENC A-		I
6	MOT ENC B+	Differential Encoder B Channel Input (For Single Ended Signals Use Only The Positive Input)	I
7	MOT ENC B-		I
8	MOT ENC I+	Differential Encoder Index Input (For Single Ended Signals Use Only The Positive Input)	I
9	MOT ENC I-		I
10	HALL A-	Commutation Sensor Input (For Differential Signals Only)	I
11	HALL B-	Commutation Sensor Input (For Differential Signals Only)	I
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-3	Programmable Analog Input (12-bit Resolution)	I
15	HALL C-	Commutation Sensor Input (For Differential Signals Only)	I

**I/O - Signal Connector**

Pin	Name	Description / Notes	I/O
1	PDO-1	Isolated Programmable Digital Output	O
2	OUTPUT COMMON	Digital Output Common	OGND
3	PDO-2	Isolated Programmable Digital Output	O
4	PAI-1 + (REF+)	Differential Programmable Analog Input or Reference Signal Input (16-bit Resolution)	I
5	PAI-1 - (REF-)		I
6	PAI-2	Programmable Analog Input (12-bit Resolution)	I
7	PAO-1	Programmable Analog Output (10-bit Resolution)	O
8	OUTPUT PULL-UP	Digital Output Pull-Up For User Outputs	I
9	PDI-5	Isolated Programmable Digital Input	I
10	PDO-3	Isolated Programmable Digital Output	O
11	PDI-1	Isolated Programmable Digital Input	I
12	PDI-2	Isolated Programmable Digital Input	I
13	PDI-3	Isolated Programmable Digital Input	I
14	PDO-4	Isolated Programmable Digital Output	O
15	INPUT COMMON	Digital Input Common (Can Be Used To Pull-Up Digital Inputs)	IGND
16	SGN GND	Signal Ground	SGND
17	PDI-4	Isolated Programmable Digital Input	I
18	PDI-6	Isolated Programmable Digital Input	I
19	PDI-7	Isolated Programmable Digital Input	I
20	ENC A+ OUT	Buffered Encoder Channel A Output	O
21	ENC A- OUT		O
22	ENC B+ OUT	Buffered Encoder Channel B Output	O
23	ENC B- OUT		O
24	ENC I+ OUT	Buffered Encoder Index Output	O
25	ENC I- OUT		O
26	SGN GND	Signal Ground	SGND

**MOTOR POWER - Motor Power Connector**

Pin	Name	Description / Notes	I/O
1	SHIELD	Motor feedback cable shield. Internally connected to protective earth ground.	-
2	MOTOR POWER U	Motor Phase U	O
3	MOTOR POWER V	Motor Phase V	O
4	MOTOR POWER W	Motor Phase W	O

**POWER - AC Power Connector**

Pin	Name	Description / Notes	I/O
1	L1	AC Supply Input (Three Phase)	I
2	L2		I
3	L3		I
4	PE	Protective Earth Ground	-

## HARDWARE SETTINGS

### Switch Functions

Switch	Description	Setting	
		On	Off
1	Bit 0 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
2	Bit 1 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
3	Bit 2 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
4	Bit 3 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
5	Bit 4 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
6	Bit 5 of binary CANopen node ID. Does not affect RS-232 settings.	1	0
7	Bit 0 of drive CANopen bit rate setting. Does not affect RS-232 settings.	1	0
8	Bit 1 of drive CANopen bit rate setting. Does not affect RS-232 settings.	1	0

### Additional Details

The drive can be configured to use the address and/or bit rate stored in non-volatile memory by setting the address and/or bit rate value to 0. Use the table below to map actual bit rates to a bit rate setting.

Bit Rate (kbits/sec)	Value For Bit Rate Setting
Load from non-volatile memory	0
500	1
250	2
125	3

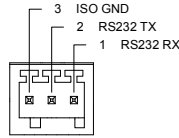
### Jumper Settings

Jumper	Description	Configuration		
		Not Installed	Pins 1-2	Pins 2-3
J1	CAN bus termination. Install this jumper (2.54mm) on the last drive in a CAN network. This jumper is located on a 4-pin header adjacent to the RS-232 connector. It consists of the two pins furthest from the connector.	Non-terminating Node	Terminating Node	N/A
J2	Reserved.	-	-	N/A

**MECHANICAL INFORMATION**

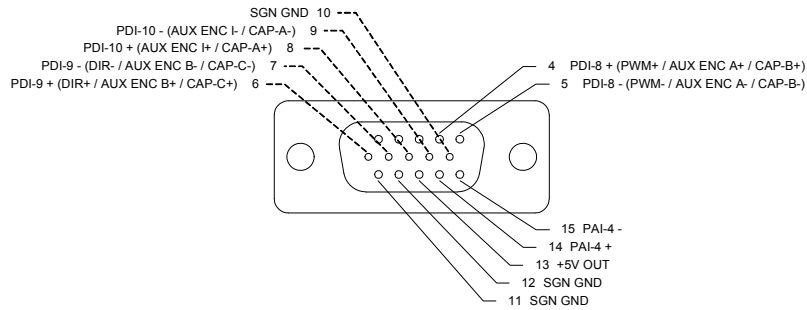
**AUX COMM - RS232 Communication Connector**

Connector Information		3-pin, 2.5 mm spaced, enclosed, friction lock header
Mating Connector	Details	Phoenix: Plug P/N 1881338
	Included with Drive	Yes



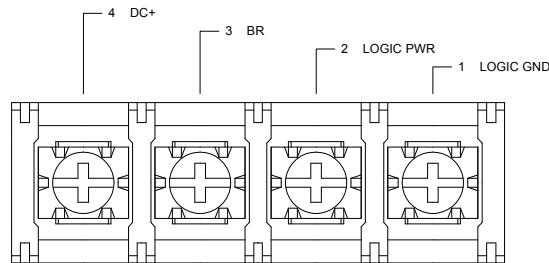
**AUX ENCODER - Auxiliary Feedback Connector**

Connector Information		15-pin, high-density, male D-sub
Mating Connector	Details	TYCO: Plug P/N 1658681-1; Housing P/N 5748677-1; Terminals P/N 1658686-2 (loose) or 1658686-1 (strip)
	Included with Drive	No



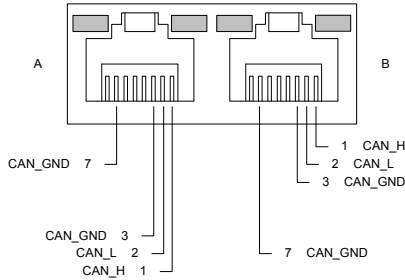
**BRAKE/LOGIC - Logic Power Connector**

Connector Information		4-contact, 13 mm spaced, dual-barrier terminal block
Mating Connector	Details	Not applicable
	Included with Drive	Not applicable



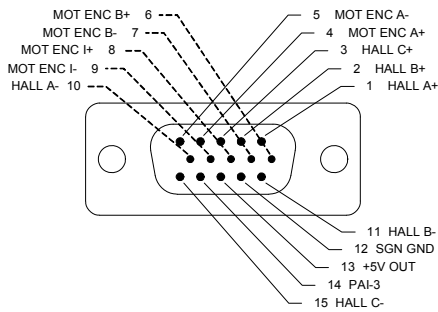
**COMM - CAN Communication Connector**

Connector Information		Shielded, dual RJ-45 socket with LEDs
Mating Connector	Details	AMP: Plug P/N 5-569552-3
	Included with Drive	No



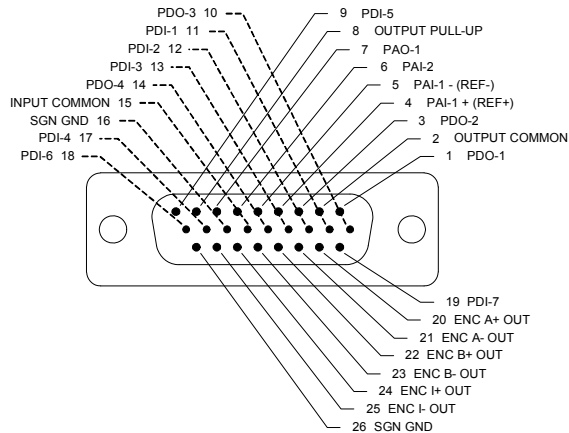
**FEEDBACK - Feedback Connector**

Connector Information		15-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 748364-1; Housing P/N 5748677-1; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No



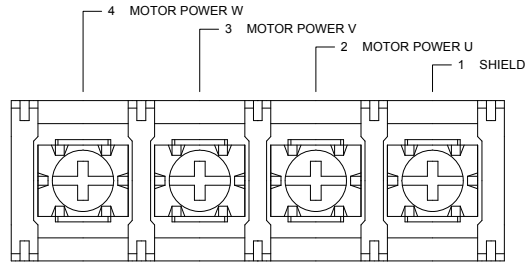
**I/O - Signal Connector**

Connector Information		26-pin, high-density, female D-sub
Mating Connector	Details	TYCO: Plug P/N 1658671-1; Housing P/N 5748677-2; Terminals P/N 1658670-2 (loose) or 1658670-1 (strip)
	Included with Drive	No



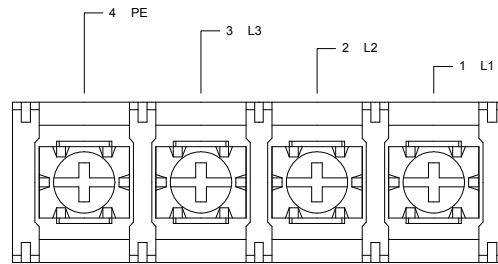
**MOTOR POWER - Motor Power Connector**

Connector Information		4-contact, 13 mm spaced, dual-barrier terminal block
Mating Connector	Details	Not applicable
	Included with Drive	Not applicable

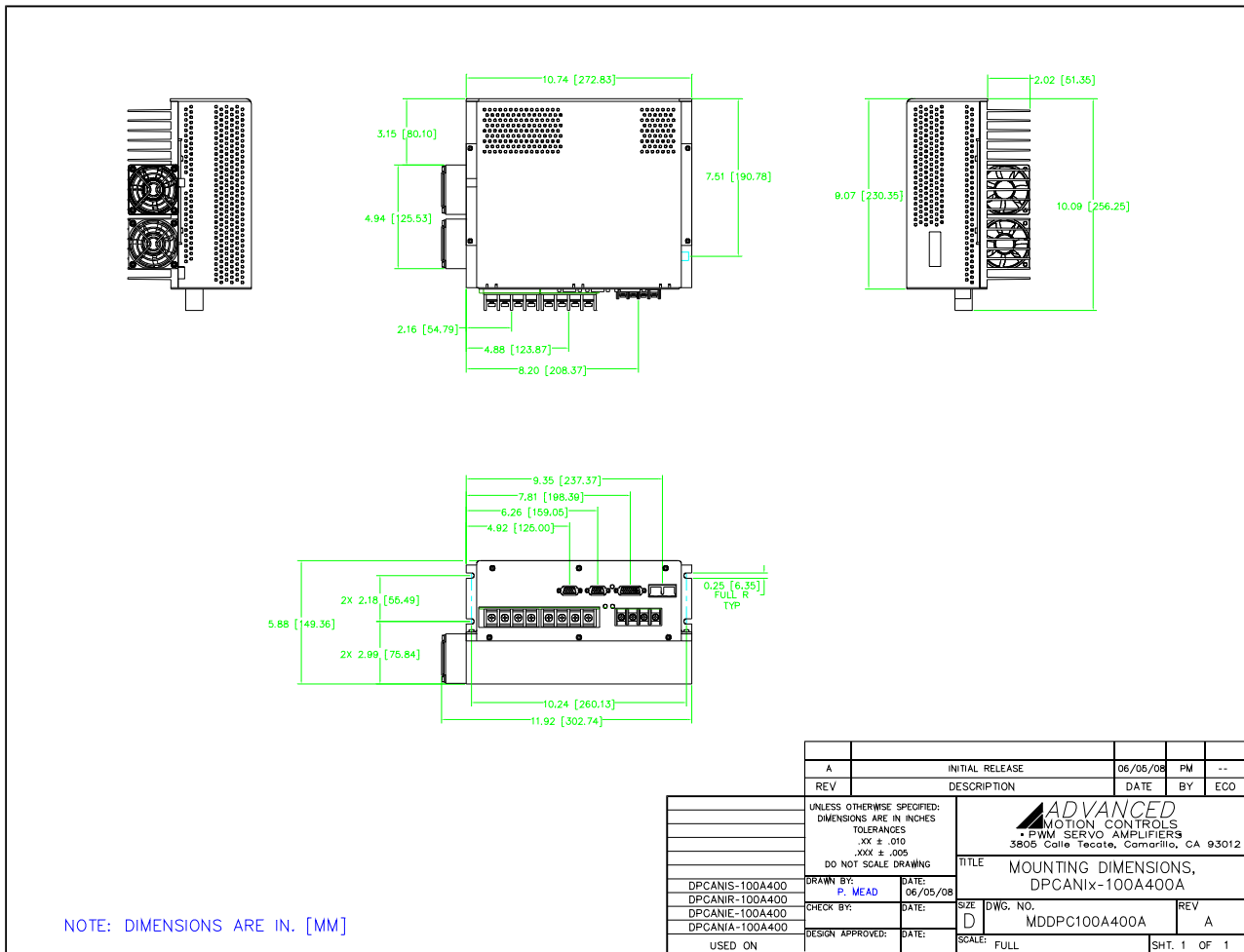


**POWER - AC Power Connector**

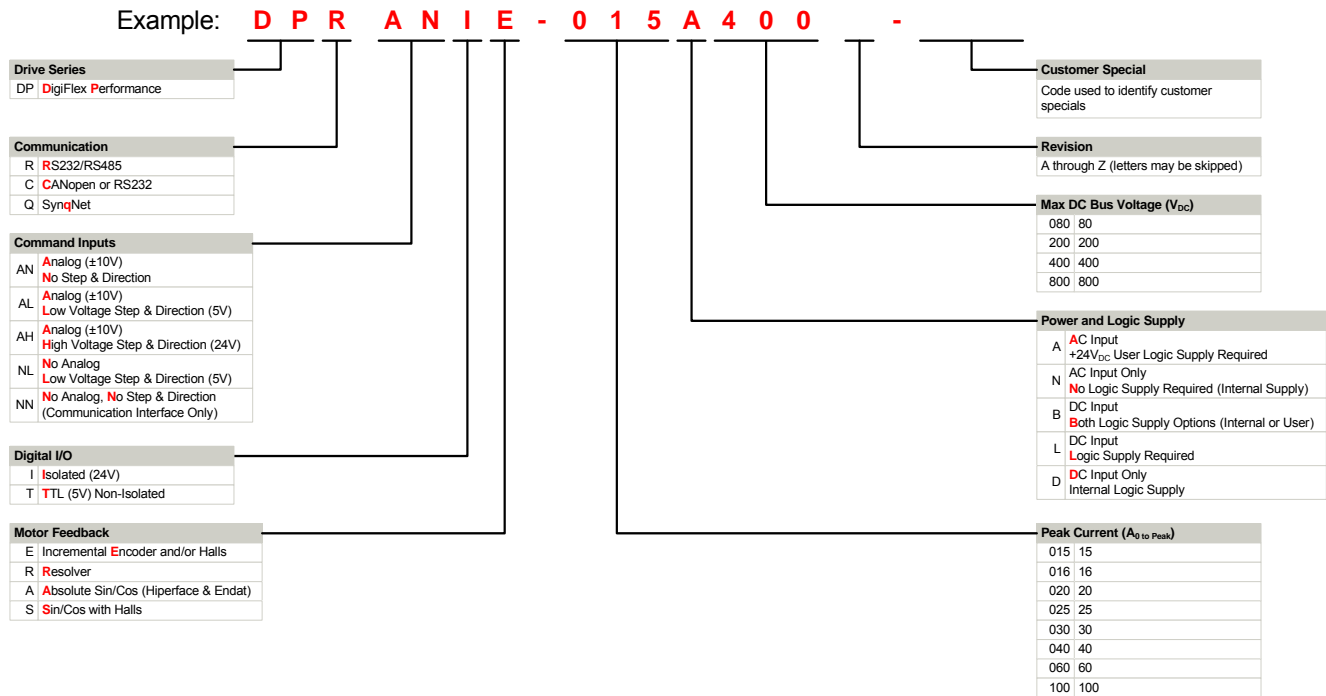
Connector Information		4-contact, 13 mm spaced, dual-barrier terminal block
Mating Connector	Details	Not applicable
	Included with Drive	Not applicable



**MOUNTING DIMENSIONS**



**PART NUMBERING INFORMATION**



DigiFlex® Performance™ series of products are available in many configurations. Note that not all possible part number combinations are offered as standard drives. All models listed in the selection tables of the website are readily available, standard product offerings.

ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability. Feel free to contact Applications Engineering for further information and details.

**Examples of Customized Products**

- ▲ Optimized Footprint
  - ▲ Private Label Software
  - ▲ OEM Specified Connectors
  - ▲ No Outer Case
  - ▲ Increased Current Resolution
  - ▲ Increased Temperature Range
  - ▲ Custom Control Interface
  - ▲ Integrated System I/O
- ▲ Tailored Project File
  - ▲ Silkscreen Branding
  - ▲ Optimized Base Plate
  - ▲ Increased Current Limits
  - ▲ Increased Voltage Range
  - ▲ Conformal Coating
  - ▲ Multi-Axis Configurations
  - ▲ Reduced Profile Size and Weight

All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.