

Description

The SX30A8 PWM servo drive is designed to drive three phase brushless motors with sine wave current at a high switching frequency. The drive requires two sinusoidal command signals with a 120-degree phase shift (external commutation). The phase angle must correspond to the position of the motor rotor, while the signal amplitude controls the motor torque. The SX30A8 interfaces directly with digital controllers. The drive is fully protected against over-voltage, over-current, over-heating, and short-circuits, and requires only a single unregulated DC power supply (all logic and control voltages are generated internally). A red/green LED and two digital outputs indicate operating status.

See Part Numbering Information on last page of datasheet for additional ordering options.

Power Range

Peak Current	30 A (21.2 A _{RMS})
Continuous Current	15 A _{RMS}
Supply Voltage	20 - 80 VDC



Features

- ▲ Optical Isolation Between High & Low Power Signals
- ▲ Four Quadrant Regenerative Operation
- ▲ Adjustable Current Limits
- ▲ High Switching Frequency
- ▲ Differential Input Command
- ▲ Selectable Inhibit/Enable Logic
- ▲ Digital Fault Output Monitor
- ▲ Sinusoidal Current Output
- ▲ Adjustable Input Gain
- ▲ DIP Switch Selectable Tuning
- ▲ Drive Status LED
- ▲ No Crossover Distortion

MODES OF OPERATION

- Current

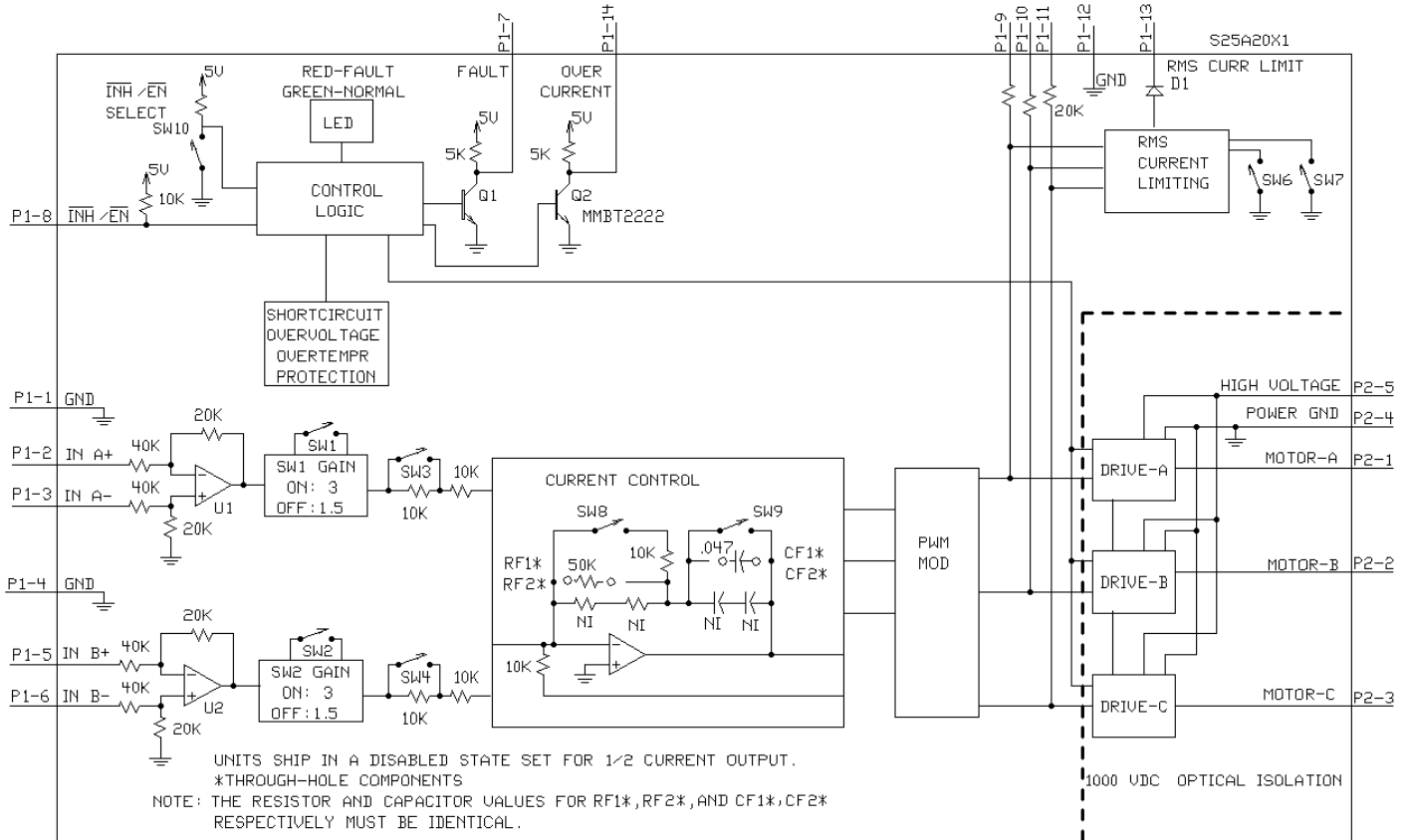
COMMAND SOURCE

- 120° Sine




COMPLIANCES & AGENCY APPROVALS

- UL
- cUL
- CE Class A (LVD)
- CE Class A (EMC)
- RoHS

BLOCK DIAGRAM



Information on Approvals and Compliances

	<p>US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.</p>
	<p>Compliant with European CE for both the Class A EMC Directive 2004/108/EC on Electromagnetic Compatibility (specifically EN 61000-6-4:2007 and EN 61000-6-2:2005) and LVD requirements of directive 2006/95/EC (specifically EN 60204-1:2006), a low voltage directive to protect users from electrical shock.</p>
	<p>RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.</p>

SPECIFICATIONS

Power Specifications		
Description	Units	Value
DC Supply Voltage Range	VDC	20 - 80
DC Bus Over Voltage Limit	VDC	86
Maximum Peak Output Current ¹	A	30
Maximum Continuous Sine Wave Current	Arms	15
Maximum Continuous Output Power	W	1140
Maximum Power Dissipation at Continuous Current	W	60
Minimum Load Inductance (Line-To-Line) ²	µH	200
Switching Frequency	kHz	27
Control Specifications		
Description	Units	Value
Command Sources	-	120° Sine
Commutation Methods	-	Sinusoidal
Modes of Operation	-	Current
Motors Supported	-	Three Phase (Brushless)
Hardware Protection	-	Over Current, Over Temperature, Over Voltage, Short Circuit (Phase-Phase & Phase-Ground)
Primary I/O Logic Level	-	5V TTL
Mechanical Specifications		
Description	Units	Value
Agency Approvals	-	CE Class A (EMC), CE Class A (LVD), cUL, RoHS, UL
Size (H x W x D)	mm (in)	186.7 x 111.8 x 36.8 (7.4 x 4.4 x 1.4)
Weight	g (oz)	680 (24)
Heatsink (Base) Temperature Range ³	°C (°F)	0 - 65 (32 - 149)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Form Factor	-	Panel Mount
P1 Connector	-	15-pin, female D-sub
P2 Connector	-	5-port, 5.08 mm spaced, screw terminal

Notes

1. Maximum duration of peak current is ~2 seconds.
2. Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
3. Additional cooling and/or heatsink may be required to achieve rated performance.

PIN FUNCTIONS

P1 - Signal Connector			
Pin	Name	Description / Notes	I/O
1	SIGNAL GND	Signal Ground	SGND
2	+REF-IN-A	Differential reference input, maximum ± 10 V, 40K input resistance	I
3	-REF-IN-A		I
4	SIGNAL GND	Signal Ground	SGND
5	+REF-IN-B	Differential reference input, maximum ± 10 V, 40K input resistance	I
6	-REF-IN-B		I
7	FAULT OUT	TTL level (+5 V) output becomes high when power devices are disabled due to at least one of the following conditions: inhibit, output short circuit, over voltage, over temperature, power-up reset.	O
8	$\overline{\text{INHIBIT/ENABLE IN}}$	TTL level (+5 V) inhibit/enable input. Leave open to enable drive. Pull to ground to inhibit drive. Inhibit turns off all power devices.	I
9	CURRENT MONITOR A OUT	Phase Current Monitor. 7.25 V = amplifier peak rated current .	O
10	CURRENT MONITOR B OUT		O
11	CURRENT MONITOR C OUT		O
12	SIGNAL GND	Signal Ground	SGND
13	RMS CURRENT LIMIT	The RMS current limit can be controlled by an external voltage; 5 V = maximum RMS current limit. This is referenced to Signal Ground. No input to this pin is necessary to obtain maximum current.	I
14	OVER-CURRENT FALUT OUT	This transistor output becomes high if RMS current (in any phase) exceeds RMS current limit. This creates a fault condition. Drive will re-enable when the RMS current returns to values within the RMS current limit range.	I
15	NC	Not Connected (Reserved)	-

P2 - Power Connector			
Pin	Name	Description / Notes	I/O
1	MOTOR A	Motor Phase A	O
2	MOTOR B	Motor Phase B	O
3	MOTOR C	Motor Phase C	O
4	PWR GND	Power Ground (Isolated From Signal Ground)	PGND
5	HIGH VOLTAGE	DC Power Input	I

HARDWARE SETTINGS

Switch Functions

Switch	Description	Setting	
		On	Off
1	Input range selection. Input range can be set to ± 5 V or ± 10 V. Must be set the same as switch 2.	± 5 V	± 10 V
2	Input range selection. Input range can be set to ± 5 V or ± 10 V. Must be set the same as switch 1.	± 5 V	± 10 V
3	Peak Current Limit. Sets the peak current limit to 50% or 100% of the maximum peak current. Must be set the same as switch 4.	100%	50%
4	Peak Current Limit. Sets the peak current limit to 50% or 100% of the maximum peak current. Must be set the same as switch 3.	100%	50%
5	Reserved Function	-	-
6	Bit 0 of binary value for RMS current limit setting. See details below.	1	0
7	Bit 1 of binary value for RMS current limit setting. See details below.	1	0
8	Current loop proportional gain adjustment. ON by default.	Decrease	Increase
9	Current loop integral gain. Activates or deactivates integration. OFF by default.	Inactive	Active
10	Inhibit logic. Sets the logic level of inhibit pins.	Active Low	Active High

Additional Details

Switches 1 & 2, and switches 3 & 4 must be set the same. Switches 6 and 7 can be used to reduce the continuous current limit to a percentage given in the table below. 100% means no reduction.

% Of Maximum Continuous Current Limit	Switch 6	Switch 7
25	OFF	OFF
50	ON	OFF
100	OFF	ON
	ON	ON

Through-hole Components[†]

Location	Description
CF1*	Current Loop Integrator. Three identical through-hole capacitors that can be added for more precise current loop tuning. See section below on Tuning with Through-hole components for more details.
CF2*	
RF1*	Current Loop Proportional Gain. Three identical through-hole resistors that can be added for more precise current loop tuning. See section below on Tuning with Through-hole components for more details.
RF2*	

Tuning With Through-hole Components

In general, the drive will not need to be further tuned with through-hole components. However, for applications requiring more precise tuning than what is offered by the potentiometers and dipswitches, the drive can be manually modified with through-hole resistors and capacitors as denoted in the above table. By default, the through-hole locations are not populated when the drive is shipped. Before attempting to add through-hole components to the board, consult the section on loop tuning in the installation notes on the manufacturer's website. Some general rules of thumb to follow when adding through-hole components are:

- A larger resistor value will increase the proportional gain, and therefore create a faster response time.
- A larger capacitor value will increase the integration time, and therefore create a slower response time.

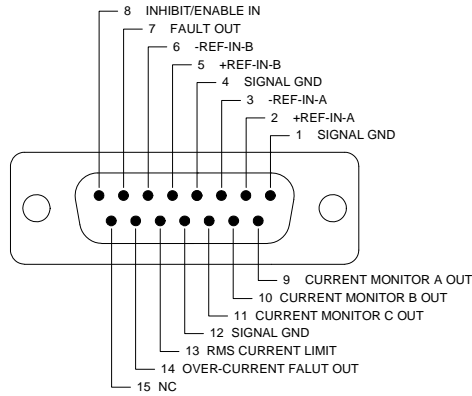
Proper tuning using the through-hole components will require careful observation of the loop response on a digital oscilloscope to find the optimal through-hole component values for the specific application.

[†]**Note: Damage done to the drive while performing these modifications will void the warranty.**

MECHANICAL INFORMATION

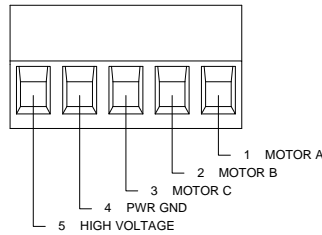
P1 - Signal Connector

Connector Information		15-pin, female D-sub
Mating Connector	Details	TYCO: Plug P/N 205206-3; Housing P/N 5745172-1; Terminals P/N 1658540-5 (loose) or 1658540-4 (strip)
	Included with Drive	No



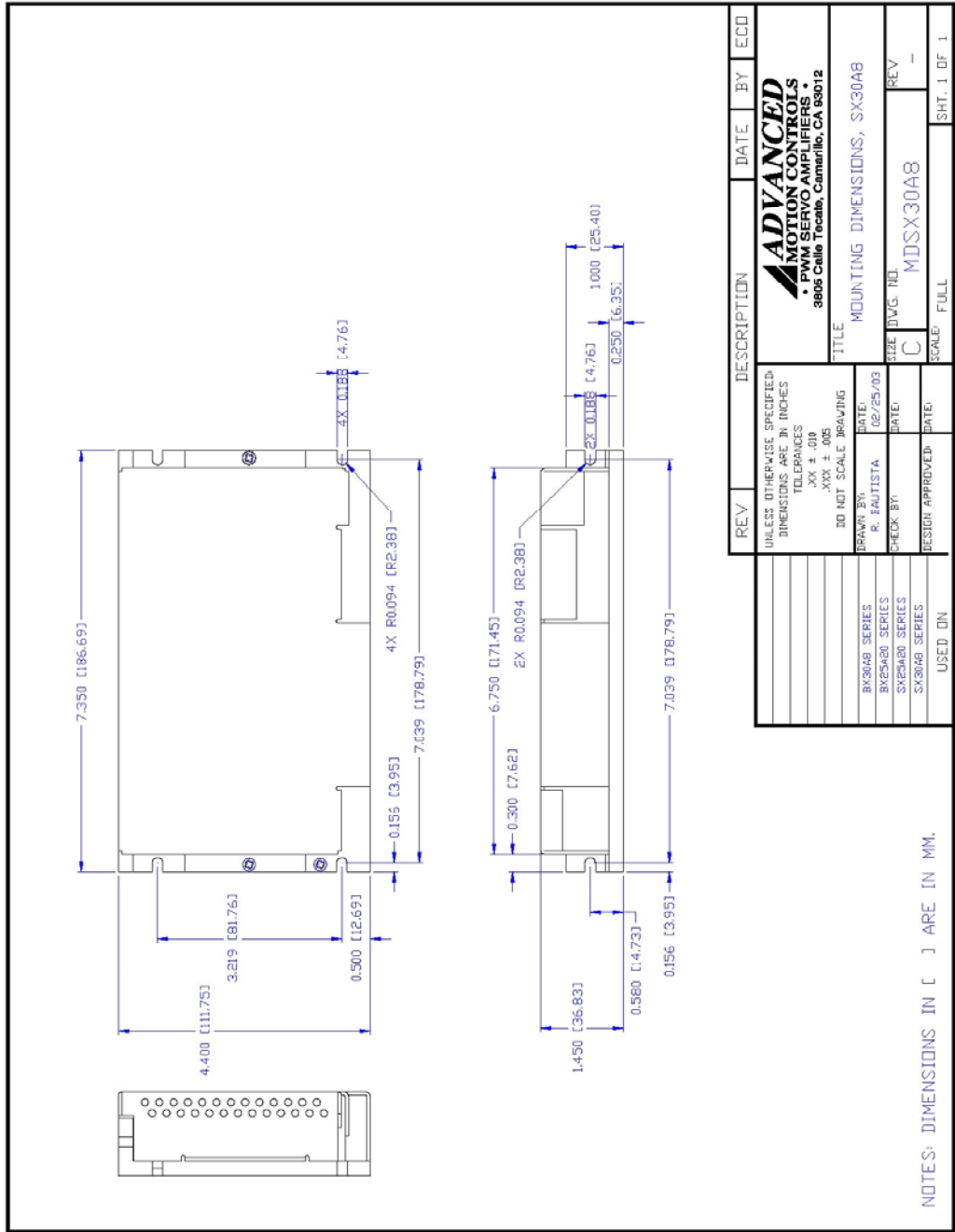
P2 - Power Connector

Connector Information		5-port, 5.08 mm spaced, screw terminal
Mating Connector	Details	Not applicable
	Included with Drive	Not applicable



MOUNTING DIMENSIONS

Mounting Dimensions



REV	DESCRIPTION	DATE	BY	ECD
	UNLESS OTHERWISE SPECIFIED, DIMENSIONS ARE IN INCHES. TOLERANCES: .XX ± .01, .XXX ± .005. DO NOT SCALE DRAWING.			
	ADVANCED MOTION CONTROLS PWM SERVO AMPLIFIERS 3805 Calle Tecate, Camarillo, CA 93012			
	TITLE: MOUNTING DIMENSIONS, SX30A8			
	DRAWN BY: R. FAUTISTA	DATE: 02/25/03		
	CHECK BY:	DATE:		
	DESIGN APPROVED:	DATE:		
	USED ON:			
	SIZE: C	DWG. NO: MDSX30A8	REV: -	
	SCALE: FULL			SHT. 1 OF 1

