

Submitted by:
 Name: _____
 Company: _____
 Phone: _____
 Email: _____
 Date: _____



Click&Move® Opportunity Form

Customer Information

(return completed form to cfournier@a-m-c.com)

First:	Last:	M.I.:
Company: _____		
<input type="checkbox"/> Existing Customer		
Street Address: _____		
City:	State:	Zip:
Email:	Phone:	

Commercial/Application Information

<input type="checkbox"/> OEM	Customer Concerns (prior to project beginning):	Known Competition (Incumbent and Potential):
<input type="checkbox"/> VAR / Integrator		<input type="checkbox"/> In-House Customer Design
Brief Application Description & Project / Program Name (attach additional information for multiple axes)		<input type="checkbox"/> Retrofit <input type="checkbox"/> New Design
Timing (Prototypes, Production, Project Life):		Cost Targets & Quantity (Prototype, Production):

Machine/Process Flow and Control Architecture Information

<input type="checkbox"/> Centralized Control	<input type="checkbox"/> Distributed Control	Can the logic be flow-charted?	Does a description of the control logic exist?
		<input type="checkbox"/> Yes <input type="checkbox"/> No	<input type="checkbox"/> Yes <input type="checkbox"/> No
Software			
OS: <input type="checkbox"/> Windows 7/8/10 <input type="checkbox"/> Linux	Preferred Programming Language (if so, select from the choices below)		RTOS Needed
	<input type="checkbox"/> C/C++/C# <input type="checkbox"/> VBA <input type="checkbox"/> JAVA <input type="checkbox"/> IEC61131-FB/LD/ST/IL/SFC <input type="checkbox"/> Python		<input type="checkbox"/> Yes <input type="checkbox"/> No
Control Platform	Motion Control	Performance	
<input type="checkbox"/> PC <input type="checkbox"/> MACC Family <input type="checkbox"/> AMC Drive <input type="checkbox"/> 3 rd Party SBC	<input type="checkbox"/> Servos Number _____ Type _____ Voltage _____ Current _____ Feedback Type _____	<input type="checkbox"/> Motion Profile Known Type: _____	
Communication Protocol and Physical Layer	<input type="checkbox"/> Steppers Number _____ Type _____ Feedback Type _____	<input type="checkbox"/> Following Error Target _____	
<input type="checkbox"/> Digital <input type="checkbox"/> CANopen <input type="checkbox"/> EtherCAT (CoE) <input type="checkbox"/> Ethernet POWERLINK <input type="checkbox"/> Modbus TCP <input type="checkbox"/> Other	Motion Type	<input type="checkbox"/> Positioning Accuracy _____	
<input type="checkbox"/> Analog	<input type="checkbox"/> Asynchronous <input type="checkbox"/> Coordinated <input type="checkbox"/> G-code File Used <input type="checkbox"/> PVT File Used <input type="checkbox"/> Synced to I/O Type _____	<input type="checkbox"/> Precision Desired _____	
HMI	<input type="checkbox"/> Robotic Transform Needed <input type="checkbox"/> Velocity Mode <input type="checkbox"/> Position Mode	System I/O	
<input type="checkbox"/> Touchscreen <input type="checkbox"/> PC HMI <input type="checkbox"/> 3 rd Party Keypad Display		<input type="checkbox"/> Digital Qty: _____ Voltage Level: _____	
		<input type="checkbox"/> Analog Qty: _____ Type: _____	

Engineering Information

Product Requirements (Please describe – include expected total system solution: drives, controllers, etc.)	<input type="checkbox"/> Need for Customs
Development Resources (Please describe – include customer experience level and expected AMC resources for integration and development)	
	<input type="checkbox"/> NRE